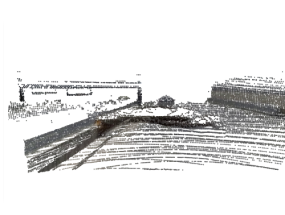
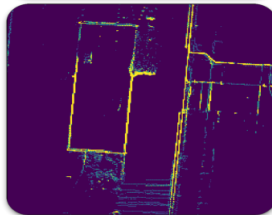
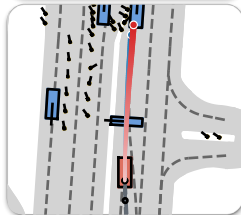
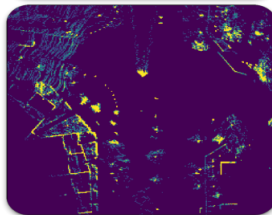
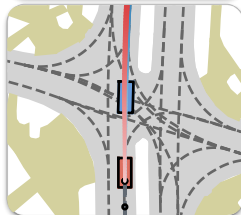
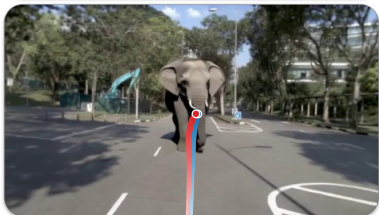
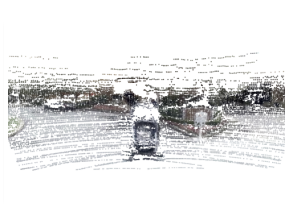
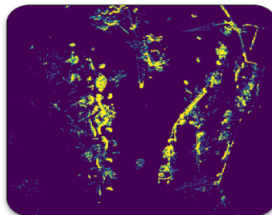
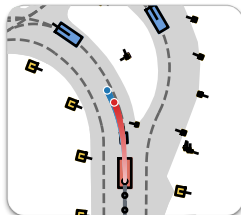
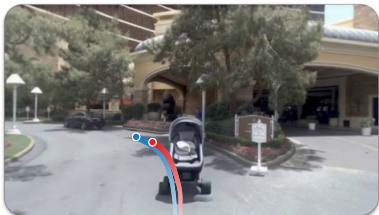


Front view

BEV layout

DiffusionDrive LiDAR input

3D LiDAR view



— DiffusionDrive (LiDAR) — Ego-Status MLP (no LiDAR) - - - History