

input + plan



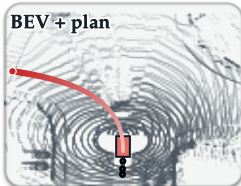
OneVL future,  $t+0.5s$



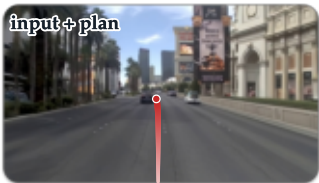
OneVL future,  $t+1.0s$



BEV + plan



input + plan



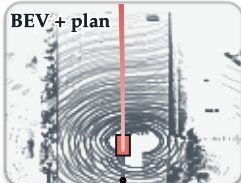
OneVL future,  $t+0.5s$



OneVL future,  $t+1.0s$



BEV + plan



— OneVL planned trajectory    - - - History